

# Quantum Mechanics

$$\Delta m = \sqrt{\langle m^2 \rangle - \langle m \rangle^2}$$

$$\langle p \rangle = \frac{1}{m} \frac{d}{dt} \langle x \rangle$$

$$\frac{\lambda_1}{\lambda_2} = \frac{\mu_1}{\mu_2}$$

$$e^{i\phi\hat{n}\cdot\vec{S}/\hbar} = I \cos(\phi/2) + i\hat{n} \cdot \vec{\sigma} \sin(\phi/2)$$

$$\sigma_{tot} = \frac{4\pi}{k^2} \sum_l (2l+1) \sin^2(\delta_l(k))$$

$$\frac{\hbar^2}{2m} \frac{\partial^2 U}{\partial r^2} - \frac{l(l+1)\hbar^2}{2mr^2} U + VU = EU$$

$$U = rR(r)$$

Spherical Bessel functions :

$$A_l j_l(kr), B_l y_l(kr)$$

$$\tan(\delta_l) = -\frac{B_l}{A_l}$$

$$\text{small } k : j_l(kr) \rightarrow \frac{1}{kr} \sin(kr)$$

$$y_l(kr) \rightarrow -\frac{1}{kr} \cos(kr)$$

$$k \cot \delta_0 \approx -\frac{1}{a}$$

$$kr > \sqrt{l(l+1)}$$

$$\sigma \approx \pi R^2$$

$$f(\theta) = -\frac{m}{2\pi\hbar^2} \int V(r) e^{i\vec{\kappa}\cdot\vec{r}} dr$$

$$\text{spherical : } f(\theta) = -\frac{2m}{\hbar^2\kappa} \int_0^\infty rV(r) \sin(\kappa r) dr$$

$$\text{low energy : } f(\theta) = -\frac{m}{2\pi\hbar^2} \int V(r) dr^3$$

$$\frac{d\theta}{d\Omega} = |f(\theta)|^2$$

$$\kappa = 2k \sin\left(\frac{\theta}{2}\right)$$

$$E^{(1)} = \langle \phi^{(0)} | H' | \phi^{(0)} \rangle$$

$$|\phi_n^{(1)}\rangle = \sum_{k \neq n} \frac{\langle \phi_k^{(0)} | H' | \phi_n^{(0)} \rangle}{E_n^{(0)} - E_k^{(0)}} |\phi_k^{(0)}\rangle$$

$$E_n^{(2)} = \sum_{k \neq n} \frac{|\langle \phi_k^{(0)} | H' | \phi_n^{(0)} \rangle|^2}{E_n^{(0)} - E_k^{(0)}}$$

$$T = e^{-2\gamma}$$

$$\gamma = \frac{1}{\hbar} \int_{x_1}^{x_2} \sqrt{2m[V(x) - E]} dx$$

$$p(x) = \sqrt{2m(E - V)}$$

$$\int_{x_1}^{x_2} p(x) dx = (n - \frac{1}{2})\pi\hbar$$

$$\psi(p) = \frac{1}{2\pi\hbar} e^{i\hbar\omega(n+c)}$$

$$\text{one hard wall : } c = \frac{1}{2}$$

$$2 \text{ hard walls : } c = 1$$

$$\text{no hard walls : } c = \frac{3}{4}$$

$$-\frac{\hbar^2}{2\mu} \frac{d^2 U}{dr^2} + \frac{l(l+1)\hbar^2}{2\mu r^2} U + V(r)U = EU$$

$$a \propto \frac{1}{\mu e^2}$$

$$E_v = \frac{\langle \psi_{tri} | H | \psi_{tri} \rangle}{\langle \psi_{tri} | \psi_{tri} \rangle}$$

$$\bar{j} = \frac{i\hbar}{2m} [\psi \nabla \psi^* - \psi^* \nabla \psi]$$

$$\tilde{X} = \sqrt{\frac{\hbar}{2m\omega}} (a^\dagger + a)$$

$$\tilde{P} = i\sqrt{\frac{m\hbar\omega}{2}} (a^\dagger - a)$$

$$a|n\rangle = \sqrt{n}|n-1\rangle$$

$$a^\dagger|n\rangle = \sqrt{n+1}|n+1\rangle$$

$$J_x = \frac{1}{2}(J_+ + J_-)$$

$$J_y = \frac{1}{2i}(J_+ - J_-)$$

$$J_\pm |j, m\rangle = \hbar \sqrt{j(j+1) - m(m \pm 1)} |j, m \pm 1\rangle$$

$$S_i = \frac{\hbar}{2} \sigma_i$$

$$[S_i, S_j] = i\hbar \epsilon_{ijk} S_k$$

$$\langle S_z \rangle = \text{Tr}[\rho S_z]$$

$$L^2 |l, m\rangle = l(l+1)\hbar^2 |l, m\rangle$$

$$L_z |l, m\rangle = m\hbar |l, m\rangle$$

$$H = \frac{1}{2m} (\vec{p} - q\vec{A})^2 + q\phi$$

$$H = \frac{p^2}{2m} + \frac{1}{2} m\omega^2 x^2$$

$$E = \frac{\hbar^2 \kappa^2}{2m}$$

$$E_n = \hbar\omega(n + \frac{1}{2})$$

$$W_{fi} = \frac{1}{\hbar^2} \left| \int_{-\infty}^{\infty} \langle f | H' | i \rangle e^{i(E_f - E_i)t/\hbar} dt \right|^2$$

$$\omega = \frac{eB}{2m}$$

$$\langle m \rangle = \int \psi^* m \psi dx$$

# Classical Mechanics

$$H = -\mathcal{L} + p_i \dot{q}_i$$

$$p_i = \frac{\partial \mathcal{L}}{\partial \dot{q}_i}$$

$$-\dot{p}_i = \frac{\partial H}{\partial q_i}; \dot{q}_i = \frac{\partial H}{\partial p_i}$$

$$\mathcal{L} = T - V$$

$$\frac{d}{dt} \frac{\partial \mathcal{L}}{\partial \dot{\theta}} = \frac{\partial \mathcal{L}}{\partial \theta}$$

$$H = T + V$$

$$\frac{\partial H}{\partial t} = -\frac{\partial \mathcal{L}}{\partial t}$$

$$T = \frac{m}{2} (\dot{r}^2 + r^2 \dot{\theta}^2 + r^2 \sin^2(\theta) \dot{\phi}^2)$$

$$H = \frac{1}{2m} (p_r^2 + \frac{1}{r^2} p_\theta^2 + \frac{1}{r^2 \sin^2(\theta)} p_\phi^2)$$

$$H = \frac{1}{2m} (p_r^2 + \frac{1}{r^2} p_\theta^2 + p_z^2)$$

$$\begin{aligned}
x &= x_0 + v_0 t + \frac{1}{2} a t^2 \\
v(t) &= v_0 + a t \\
v_f^2 - v_i^2 &= 2a(x - x_0) \\
x &= x_0 + \frac{1}{2}(v_0 + v)t \\
\tau &= \vec{r} \times \vec{F} = I\vec{\alpha} = \frac{dL}{dt} \\
T &= \frac{1}{2} m v^2 + \frac{1}{2} I \omega^2 \\
\omega &= \sqrt{\frac{k}{m}} \\
f &= \frac{\omega}{2\pi} \\
L &= I\omega \\
v_T &= 2\pi r f = \omega r \\
a_c &= \frac{v^2}{r} = -m\vec{\Omega} \times (\vec{\Omega} \times \vec{r}) \\
F_c &= \frac{m v^2}{r} \\
F_{\text{cor}} &= -2\vec{\Omega} \times \vec{v}
\end{aligned}$$

$$W = \int \tau d\theta = \vec{F} \cdot \vec{s} = F s \cos(\theta)$$

$$\begin{aligned}
P &= \frac{dW}{dt} \\
U &= mgh \\
U &= \frac{1}{2} k x^2 \\
U &= -\frac{G m_1 M_2}{r^2} \\
I_{COM} &= \int p(r)(\delta_{jk} r^2 - (x_j - x_k)) d^3 r \\
I_{jk} &= \sum_i m_i (\delta_{jk} r_i^2 - (x_j x_k)_i) \\
I &= I_{COM} + m d^2 \\
v &= v_i + v_{\text{exhaust}} \ln\left(\frac{\mu E}{M}\right) \\
F &= v_{\text{exhaust}} \left| \frac{\Delta \mu}{\Delta t} \right| \\
m &= m_0 e^{-\frac{v}{u}} \\
T &= \frac{1}{n} V = \frac{1}{2} V
\end{aligned}$$

$$V_{\text{eff}} = k r^s + \frac{l^2}{2 m r^2}$$

$$\begin{aligned}
l &= m R^2 \dot{\theta} \\
T^2 &\propto a^3 \\
e &= \sqrt{1 + \frac{2 E l^2}{m k^2}} \\
M \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} M^T &= \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \\
M &= \begin{bmatrix} \frac{\partial Q}{\partial q} & \frac{\partial Q}{\partial p} \\ \frac{\partial P}{\partial q} & \frac{\partial P}{\partial p} \end{bmatrix} \\
P &= \frac{-\partial F}{\partial Q}; q = \frac{-\partial F}{\partial p} \\
\vec{\nabla}^2 \Phi &= 4\pi \rho G \\
\int \vec{\nabla}^2 \Phi \cdot d\vec{a} &= 4\pi \rho G \Sigma_k \\
D^2 + bD + \omega_0^2 &= 0 \\
x(t) &= e^{ipt} [C \cos(qt) + E \sin(qt)]
\end{aligned}$$

## Statistical Mechanics

$$P(v)dv = n(v)v^2 \sin(\theta) dv d\theta d\phi$$

$$\bar{v} = \int_0^\infty v P dV$$

$$v^* = \frac{\partial P}{\partial V} = 0$$

$$v_{\text{rms}} = \int_0^\infty v^2 P dV$$

$$\langle n_j(\epsilon) \rangle_{FD} = \frac{1}{e^{\beta(\epsilon - \mu)} + 1}$$

$$\langle n_j(\epsilon) \rangle_{BE} = \frac{1}{e^{\beta(\epsilon - \mu)} - 1}$$

$$g(\epsilon) = \gamma_S \frac{4\sqrt{2}\pi V m^{3/2}}{h^3} \epsilon^{1/2}$$

$$N(\tau = 0) = \int_0^{\epsilon_F} g_{FD}(\epsilon) d\epsilon$$

$$\langle E \rangle = \int_0^\infty \epsilon \langle n \rangle_{FD} g_{FD} d\epsilon$$

$$\eta = \frac{\omega}{Q_k} \leq 1 - \frac{T_c}{T_H}$$

$$\omega = Q_h - Q_c$$

$$S = \frac{Q}{T}; C = \frac{Q}{\Delta T}$$

$$\frac{dQ_H}{T_H} = -\frac{Q_c}{T_c}$$

$$\Delta T = 0; \Delta S = \frac{Q}{T}; -\omega = Q = \int PdV$$

$$L = \frac{Q}{m}; \Phi = \frac{P}{A}$$

$$P = \sigma A T^4$$

$$\sigma_{\text{rms}} = \sqrt{\langle E^2 \rangle - \langle E \rangle^2}$$

$$\langle E \rangle = \frac{f}{2} N k_B T$$

$$\binom{N}{n} \frac{v^n}{\nu} \left(1 - \frac{v}{\nu}\right)^{N-n}$$

$$\frac{\mu}{\epsilon_F} = 1 - \frac{\pi^2}{12} \left(\frac{1}{\epsilon_F \beta}\right)^2 + \dots$$

$$z_i = \Sigma_j e^{-\beta E_j}; Z = \frac{1}{N!} (z_i)^N$$

$$\langle E \rangle = -\frac{\partial}{\partial \beta} \ln(z)$$

$$\langle \tilde{O} \rangle = \frac{1}{Z} \Sigma_j \tilde{O}_j e^{-\beta \epsilon_j}$$

$$T_D = \frac{h}{2k_B} \sqrt{\frac{kT}{\rho}} \left(\frac{6\rho N_A}{\pi M}\right)^{1/3}$$

$$T \lll D : C_V \approx \frac{12}{5} \pi^4 N k_B \left(\frac{T}{T_D}\right)^3$$

$$\Delta S = 0$$

$$C_V = 3R$$

## E&M

$$P = \frac{E}{t}$$

$$U_{\text{rad}} = \int_0^t P dt$$

$$\vec{m} = \frac{1}{2} \int \vec{r}' \times \vec{J}'(r') d^3 r'$$

$$\vec{A} = \frac{\mu_0}{4\pi} \int \frac{\vec{J}'(r') d^3 r'}{|\vec{r} - \vec{r}'|}$$

$$P = \oint (\vec{E} \times \vec{H}) \cdot d\vec{A}$$

$$\vec{L} = \epsilon_0 \int \vec{r} \times \vec{E} \times \vec{B} dr^3$$

$$\phi = k \int \frac{\rho(\vec{r}') d^3 r'}{|\vec{r} - \vec{r}'|}$$

$$\phi = \sum_{lm} [A_{lm} \left(\frac{r}{R}\right)^l + B_{lm} \left(\frac{r}{R}\right)^{-(l+1)}] Y_e^m(\theta, \phi)$$

$$\mathcal{E}_{in} \frac{\partial}{\partial r} \phi_{in}|_{r=R} - \mathcal{E}_{out} \frac{\partial}{\partial r} \phi_{out}|_{r=R} = \sigma$$

$$\vec{J} = \sigma \vec{E}$$

$$\vec{\nabla} \cdot \vec{J} = -\frac{\partial \rho}{\partial t}$$

$$\vec{J} = \vec{\nabla} \times \vec{M}$$

$$\vec{K} = \vec{M} \times \hat{n} = \sigma \vec{v} = \sigma \vec{\omega} \times \vec{r}$$

$$B = \frac{\mu_0}{4\pi} \int \frac{\vec{K} \times (-\vec{r})}{r^3} dS$$

$$\Phi_B = \int \vec{B} \cdot d\vec{A} = IR$$

$$R = \frac{\rho L^2}{V}$$

$$E = E_0 e^{i(kz - \omega t)}$$

$$E_1^{\parallel} = E_2^{\parallel}; \frac{1}{\mu_1} B_1^{\parallel} = \frac{1}{\mu_2} B_2^{\parallel}$$

$$\vec{\nabla} \cdot \vec{B} = 0$$

$$\vec{\nabla} \times \vec{B} = \mu \vec{J} + \mu \epsilon \frac{\partial \vec{E}}{\partial t}$$

$$\vec{\nabla} \cdot \vec{E} = \frac{\rho_{free}}{\epsilon_0}$$

$$\vec{\nabla} \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$$

$$D = \epsilon E; B = \mu H$$

$$\oint \vec{D} \cdot d\vec{S} = Q$$

$$\oint \vec{B} \cdot d\vec{l} = \mu I$$

$$\vec{\nabla} \times \vec{H} \propto \left(\frac{i\sigma}{\omega} + \epsilon_0 \epsilon_r\right) \frac{\partial E}{\partial t}$$

$$B = \frac{\mu N I}{L}$$

$$V(t) = N \frac{d\Phi}{dt}$$

$$n_1 \sin(\theta_1) = n_2 \sin(\theta_2)$$

$$I = \frac{P}{A} = \frac{1}{2} v \epsilon |E|^2$$

$$U_C = \frac{1}{2} C V^2$$

$$U_L = \frac{1}{2} L I^2 = \frac{1}{2} \int H \cdot B dr^3$$

$$\vec{F} = \nabla(\vec{m} \cdot \vec{B})$$

$$\vec{B} = \frac{\mu_0}{4\pi} \frac{3\hat{r}(\hat{r} \cdot \vec{m}) - \vec{m}}{r^3}$$

$$\vec{A} = \frac{\mu_0}{4\pi} \frac{\vec{m} \times \vec{r}}{r^3}$$

$$q' = -q \frac{R}{b}; x = \frac{R^2}{b}$$

$$\vec{m}' = \frac{\mu_2 - \mu_1}{\mu_2 + \mu_1} \vec{m}$$

$$P = \frac{2}{3} \frac{1}{4\pi\epsilon_0} \frac{e^2 |a|^2}{c^3}$$

$$P = \frac{2}{3} \frac{1}{4\pi\epsilon_0} \frac{e^2}{c} \gamma^6 [\dot{\beta}^2 - (\beta \times \dot{\beta})^2]$$

$$P = \frac{2}{3} \frac{1}{4\pi\epsilon_0} \frac{|\ddot{p}_0|^2}{c^3}$$

$$p_0 = \sum_i q_i r_i$$

$$\begin{pmatrix} ct' \\ x' \\ y' \\ z' \end{pmatrix} = \begin{bmatrix} \gamma & -\beta_x \gamma & 0 & 0 \\ -\beta_x \gamma & \gamma & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix}$$

$$F = \gamma^3 m a_{\parallel} + \gamma m a_{\perp}$$

$$\tilde{P}(E, D, H, B) = (-E, -D, H, B)$$

$$\tilde{T}(E, D, H, B) = (E, D, -H, -B)$$

## General Formulas & Constants

$$k_B = 1.381 * 10^{-23} \frac{J}{K}$$

$$N_A = 6.022 * 10^{23} \frac{part}{mol}$$

$$amu = 1.661 * 10^{-27} kg$$

$$\hbar = 6.582 * 10^{-16} eVs$$

$$eV = 1.602 * 10^{-19}$$

$$m_e = 0.511 \frac{MeV}{c^2}$$

$$m_p = 938 \frac{MeV}{c^2}$$

$$a_0 = 5.29 * 10^{-11} m = \frac{\hbar}{me^2} = \frac{\hbar}{mca}$$

$$\alpha_{fine} = \frac{1}{137}$$

$$\epsilon_0 = 8.85 * 10^{-12} \frac{F}{m}$$

$$\mu_0 = 4\pi * 10^{-7} \frac{H}{m}$$

$$\cos^2(u) = \frac{1 + \cos(2u)}{2}$$

$$\sin^2(u) = \frac{1 - \cos(2u)}{2}$$

$$\sin(a) \sin(b) = \frac{1}{2} (\cos(a-b) - \cos(a+b))$$

$$\cos\left(\frac{\theta}{2}\right) = \frac{1}{2} (1 + \cos(\theta))$$

$$\cos(2\theta) = \cos^2(\theta) - \sin^2(\theta)$$

$$\Gamma(n) = (n-1)!$$

$$\Gamma\left(n + \frac{1}{2}\right) = \sqrt{\pi} \frac{2n!}{4^n n!}$$

$$Q(n) = 1 + \frac{n+3}{n-1} \frac{1}{2^{n+1}}$$

$$R = 8.31 J(K * mol)^{-1}$$

Geometry	Moment of Inertia
Solid Cube	$\frac{1}{6} MR^2$
Solid Cylinder/Disk	$\frac{1}{2} MR^2$
About Symm. Axis	
Hoop around diameter	$\frac{1}{2} MR^2$
Hoop about symm. axis	$MR^2$
Solid Sphere	$\frac{2}{5} MR^2$
Rod about center	$\frac{1}{12} ML^2$
Rod about end	$\frac{1}{3} ML^2$
Hollow Sphere	$\frac{2}{3} MR^2$

$$Y_0^0 = \frac{1}{2\sqrt{\pi}}$$

$$Y_1^{-1} = \frac{1}{2} \sqrt{\frac{3}{2\pi}} e^{-i\phi} \sin \theta$$

$$Y_1^0 = \sqrt{\frac{3}{4\pi}} \cos \theta$$

$$Y_1^{+1} = -\frac{1}{2} \sqrt{\frac{3}{2\pi}} e^{i\phi} \sin \theta$$